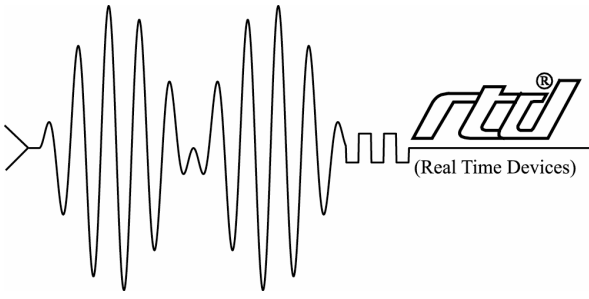
DM6430 Driver for Linux

User's Manual
Version 3.0.xx



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"Accessing the Analog World"®

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ISO9001 and AS9100 Certified

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09/29/2005	Revision B issued Removed duplicate word in “Using the API Functions” section
01/24/2008	Revision C issued Added 2.6 kernel support to the driver Changed the prototype of the LoadDigitalTable6430 function

DM6430 Driver for Linux
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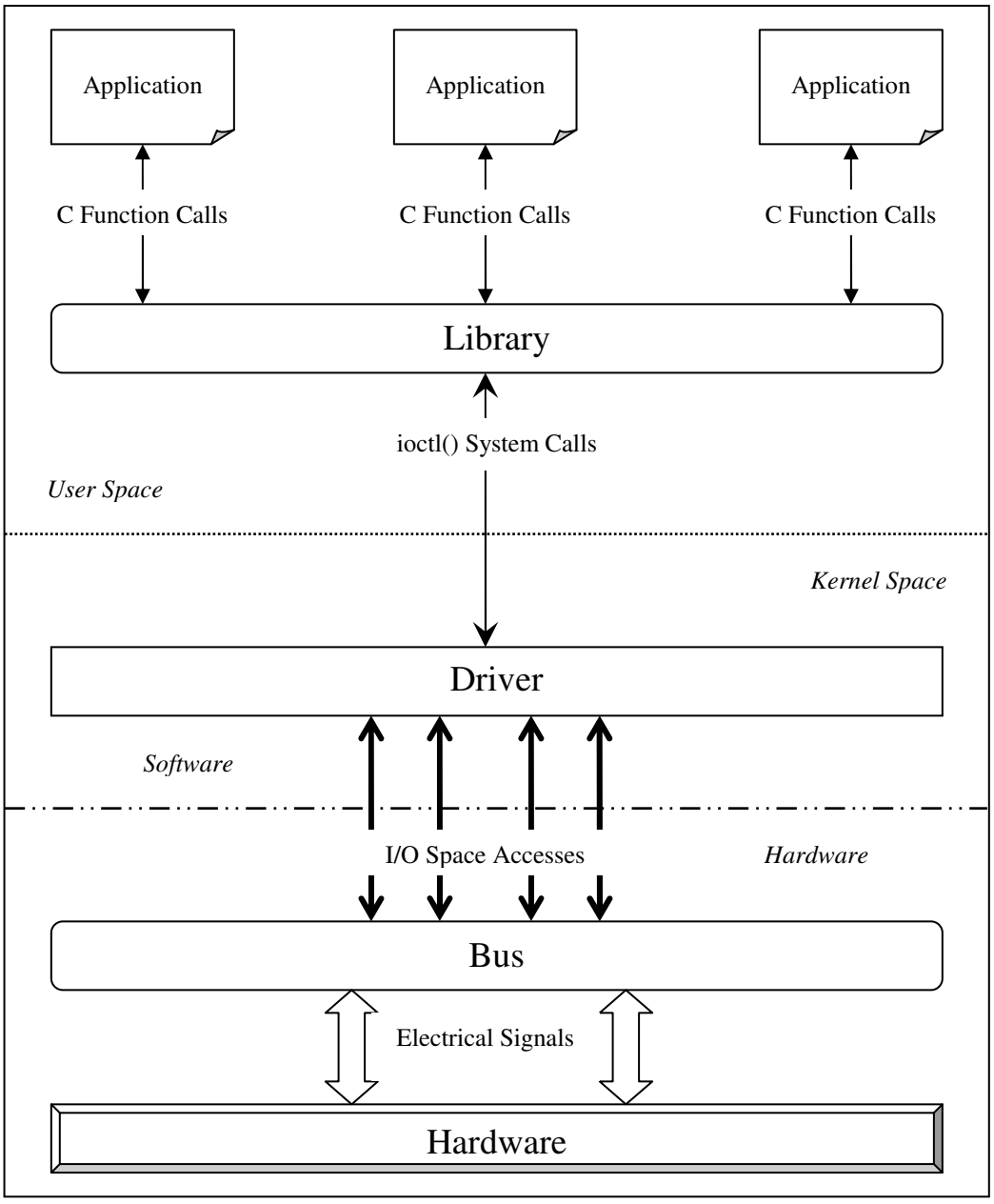
Introduction

This document targets anyone wishing to write Linux applications for an RTD DM6430 analog I/O dataModule. It provides information on building the software and about the Application Programming Interface used to communicate with the hardware and drivers. Each high-level library function is described as well as any low-level ioctl() system call interface it may make use of.

The diagram below 1) provides a general overview of what hardware and software entities are involved in device access, 2) shows which units communicate with each other, and 3) illustrates the methods used to transfer data and control information.



Installation Instructions

Extracting the Software

All software comes packaged in a gzip'd tar file named DM6430_Linux_V03.00.00.tar.gz. First, decide where you would like to place the software and make a copy of the tar file in this directory by issuing the command "cp <path to tar file>/ DM6430_Linux_V03.00.00.tar.gz <installation path>" substituting the appropriate paths for <path to tar file> and <installation path>. Next, change your current directory to where you made a copy of the tar file by issuing the command "cd <installation path>". Once you are in this directory, extract the software by issuing the command "tar –xvzf DM6430_Linux_V03.00.00.tar.gz"; this will create a directory DM6430_Linux_V03.00.00/ which contains all the files that are part of the software package.

Contents of Installation Directory

Once the tar file is extracted, you should see the following files and directories within DM6430_Linux_V03.00.00/:

driver/
examples/
include/
lib/
CHANGES.TXT
LICENSE.TXT
README.TXT

The file CHANGES.TXT describes the changes made to the software for this release, as well as for previous releases. The file LICENSE.TXT provides details about the RTD end user license agreement which must be agreed to and accepted before using this software. The file README.TXT contains a general overview of the software and contact information should you experience problems, have questions, or need information. The directory driver/ contains the source code and Makefile for the drivers. The directory examples/ holds the source code and Makefile for the example programs. The directory include/ contains all header files used by the driver, example programs, library, and your application programs. Library source code and Makefile reside in the directory lib/.

Building the Driver

Driver source code uses files located in the kernel source tree. Therefore, you must have the full kernel source tree available in order to build the driver. The kernel source tree consumes a lot of disk space, on the order of 100 to 200 megabytes. Because production systems rarely contain this much disk space, you will probably use a development machine to compile the driver source code. The development system, which provides a full compilation environment, must be running the exact same version of the kernel as your production machine(s); otherwise the kernel module may not load or may load improperly. After the code is built, you can then move the resulting object files, libraries, and executables to the production system(s).

Building the driver consists of several steps: 1) compiling the source code, 2) loading the resulting kernel module into the kernel, and 3) creating hardware device files in the /dev directory. To perform any of the above steps, you must change your current directory to driver/. The file Makefile contains rules to assist you.

The driver and Makefile have support for 2.4 and 2.6 kernels. To compile the source code, issue the command “make”. This will create the driver object file rtd-dm6430.o or rtd-dm6430.ko depending on the version of the Linux kernel you are using. The GNU C compiler gcc is used to build the driver code.

Before the driver can be used, it must be loaded into the currently running kernel. Using the command “make insmod” will load the DM6430 driver into the kernel. This target assumes that:

* A single DM6430 is installed.
* The board's base I/O address is set to the factory default of 0x300.
* The DM6430 will use IRQs 3 and 5.
* The board will use DMA channels 5 and 6.

If the previous assumptions do not match your hardware setup, you will need to edit the Makefile and change this rule to reflect your board configuration or manually issue an appropriate insmod command.

When you load the kernel driver, you might see the following message:
"Warning: loading ./rtd-dm6430.o will taint the kernel: no license"
You can safely ignore this message since it pertains to GNU General Public License (GPL) licensing issues rather than to driver operation.

The final step is to create /dev entries for the hardware. Previous versions of the driver always assumed a character device major number of 241 when registering the boards and creating the /dev entries. Instead, the driver now asks the kernel to dynamically assign a major number. Since this major number may change each time you load the driver, the best way to create the device files is to use the command "make devices"; this generates four files in /dev named rtd-dm6430-0 through rtd-dm6430-3.

If you ever need to unload the driver from the kernel, you can use the command "make rmmod".

Building the Library

The example programs and your application use the DM6430 library, so it must be built before any of these can be compiled. To build the library, change your current directory to lib/ and issue the command “make”. The GNU C compiler gcc is used to compile the library source code.

The DM6430 library is statically linked and is created in the file librtd-dm6430.a.

Building the Example Programs

The example programs may be compiled by changing your current directory to examples/ and giving the command “make”, which builds all the example programs. If you wish to compile a subset of example programs, there are targets in Makefile to do so. For example, the command “make dm6430-auto-burst” will compile and link the source file dm6430-auto-burst.cc and the command "make dm6430-stream" will compile and link the source file dm6430-stream.cc. The GNU C compiler gcc is used to compile the example program code.

Using the API Functions

DM6430 hardware and the associated driver functionality can be accessed through the library API (Application Programming Interface) functions. Applications wishing to use library functions must include the include/dm6430lib.h header file and be statically linked with the lib/librtd-dm6430.a library file.

Because of changes made in this version of the driver, existing source code which uses the library will not compile and may experience run-time problems. There are six areas which will require attention on your part:

The following function reference provides for each library routine a prototype, description, explanation of parameters, and return value or error code. By looking at a function's entry, you should gain an idea of: 1) why it would be used, 2) what it does, 3) what information is passed into it, 4) what information it passes back, 5) how to interpret error conditions that may arise, and 6) the ioctl() system call interface if the function makes use of a single ioctl() call.

Note that errno codes other than the ones indicated in the following pages may be set by the library functions. Unless otherwise noted in the description of a function's return value, please see the ioctl(2) man page for more information

Function Reference

API Function Groups

Analog to Digital Conversion

ChannelGainDataStore6430
ClearADFIFO6430
ClearChannelGainTable6430
EnableTables6430
GetAutoincData6430
IsADConverting6430
IsADFIFOEmpty6430
IsADFIFOFull6430
IsADHalted6430
IsAboutTrigger6430
LoadADSampleCounter6430
LoadADTable6430
LoadDigitalTable6430
LoadTriggerRegister6430
ReadADData6430
ReadChannelGainDataStore6430
ResetChannelGainTable6430
SetBurstTrigger6430
SetChannelGain6430
SetConversionSelect6430
SetPauseEnable6430
SetStartTrigger6430
SetStopTrigger6430
SetTriggerPolarity6430
SetTriggerRepeat6430
StartConversion6430

Digital to Analog Conversion

LoadDAC26430
LoadDAC6430

Digital I/O

ClearDINFIFO6430
ConfigDINClock6430
DIOClearChip6430
DIOClearIrq6430
DINClockEnable6430
DIOEnableIrq6430
DIOIsChipIRQEnabled6430
DIOIsChipIRQEventMode6430
DIOIsChipIrq6430
DIOIsChipPort1Output6430
DIOIsChipStrobe6430
DIOIsChipSystemClock6430
DIOLoadCompare6430
DIOLoadMask6430
DIORead6430
DIOReadCompareRegister6430
DIOReadStatus6430
DIOSelectClock6430
DIOSelectIrqMode6430
DIOSelectRegister6430
DIOSetPort0Direction6430
DIOSetPort1Direction6430
DIOWrite6430
IsDINFIFOEmpty6430
IsDINFIFOFull6430
IsDINFIFOHalf6430
IsDigitalIRQ6430
LoadDINConfigRegister6430
ReadDINFIFO6430

Direct Memory Access (DMA) Data Transfer

ClearADDMADone6430
DeInstallDMA6430
GetDmaData6430
InstallDMA6430
IsADDMADone6430
IsFirstADDMADone6430
StartDMA6430
StopDMA6430

General

ClearBoard6430
ClearRegister6430
CloseBoard6430
InitBoard6430
LoadControlRegister6430
OpenBoard6430
ReadStatus6430

Interrupt Control and Status

ClearIRQ06430
ClearIRQ16430
DisableIRQ6430
EnableIRQ6430
GetIRQCounter6430
InstallCallbackIRQHandler6430
LoadIRQRegister6430
RemoveIRQHandler6430
SetIRQ0Source6430
SetIRQ1Source6430

Timer/Counter Control and Status

ClockDivisor6430
ClockMode6430
DoneTimer6430
IsBurstClockOn6430
IsPacerClockOn6430
ReadTimerCounter6430
SelectTimerCounter6430
SetBurstClock6430
SetPacerClock6430
SetPacerClockSource6430
SetSampleCounterStop6430
SetUserClock6430

ChannelGainDataStore6430

int ChannelGainDataStore6430(int descriptor, int Enable);

Description:

Enable or disable a board's channel/gain data store.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Enable:	Flag to indicate whether the channel/gain data store should be enabled. A value of 0 means disable the data store. A nonzero value means enable the data store.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request ;

/*
 * Write to the Control Register at I/O base address + 2
*/

io_request.reg = r_CONTROL_6430;

/*
 * Only change bit 4 in the Control Register
 */

io_request.mask = 0xFFEF;

/*
 * Enable the channel/gain data store
 */

io_request.value = (1 << 4);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

ClearADDMADone6430

int ClearADDMADone6430(int descriptor);

Description:

Clear a board's A/D DMA done flag.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_AD_DMA_DONE);

ClearADFIFO6430

int ClearADFIFO6430(int descriptor);

Description:

Clear a board's A/D sample FIFO.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_AD_FIFO);

ClearBoard6430

int ClearBoard6430(int descriptor);

Description:

Reset a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_BOARD);

ClearChannelGainTable6430

int ClearChannelGainTable6430(int descriptor);

Description:

Clear the contents of a board's channel/gain table.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_CLEAR_GAIN);

ClearDINFIFO6430

int ClearDINFIFO6430(int descriptor);

Description:

Clear a board's digital input FIFO.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_DIO_FIFO);

ClearIRQ06430

int ClearIRQ06430(int descriptor);

Description:

Clear the first interrupt circuit on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_IRQ1);

ClearIRQ16430

int ClearIRQ16430(int descriptor);

Description:

Clear the second interrupt circuit on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_IRQ2);

ClearRegister6430

int ClearRegister6430(int descriptor, u_int16_t ClearValue);

Description:

Write a bit mask into a board's Program Clear Register and then read from the Clear Register to clear some part(s) of the board. Other library functions make use of this routine to perform their work.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

ClearValue: Bit mask to write into Program Clear Register before reading Clear Register.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;

/*
 * Clear the contents of board's channel/gain table.
 */

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_CLEAR_GAIN);
```

ClockDivisor6430

---

int ClockDivisor6430(int descriptor, enum DM6430HR_CLK Timer, u_int16_t Divisor);

Description:

Set the divisor for the specified counter on the 8254 chip. Before calling this function, the counter must have been set to receive the divisor least significant byte first then most significant byte.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Timer:	Indicates which counter to use. Valid values are DM6430HR_CLK0, DM6430HR_CLK1, and DM6430HR_CLK2.
Divisor:	Counter divisor value.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	Timer is not valid.

IOCTL Interface:

This function makes use of several ioctl() requests.

ClockMode6430

```
int ClockMode6430(
   int descriptor,
   enum DM6430HR_CLK Timer,
   enum DM6430HR_CLK_MODE Mode
);
```

Description:

Set the mode of the specified counter on the 8254 chip. This function also sets the indicated counter to receive a subsequent divisor load least significant byte first then most significant byte.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Timer:	Indicates which counter to use. Valid values are DM6430HR_CLK0, DM6430HR_CLK1, and DM6430HR_CLK2.
Mode:	Indicates which clock mode to set. Valid values are DM6430HR_CLK_MODE0, DM6430HR_CLK_MODE1, DM6430HR_CLK_MODE2, DM6430HR_CLK_MODE3, DM6430HR_CLK_MODE4, and DM6430HR_CLK_MODE5.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	Timer is not valid.
	EINVAL	Mode is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Write to Timer/Counter Control Register at I/O base address + 22
 */

io_request.reg = r_TIMER_CTRL_6430;

/*
 * Operate on timer/counter 2
 */

io_request.value = ((DM6430HR_CLK2 & 0x3) << 6);

/*
 * Put timer/counter into Mode 2 (rate generator mode)
 */

io_request.value |= ((DM6430HR_CLK_MODE2 & 0x7) << 1);

/*
 * Set timer/counter value to be accessed least significant byte first then most significant byte
 */
```

```
io_request.value |= 0x30;

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTB, &io_request);
```

CloseBoard6430

int CloseBoard6430(int descriptor);

Description:

Close a DM6430 device file opened previously with OpenBoard6430().

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.

Return Value:

0:	Success.
-1:	Failure. Please see the close(2) or ioctl(2) man page for information on possible values errno may have in this case.

IOCTL Interface:

This function makes use of several ioctl() requests.

ConfigDINClock6430

int ConfigDINClock6430(int descriptor, enum DM6430HR_DI_FIFO_CLK DIN_Clock);

Description:

Set the source for a board's digital input FIFO clock.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
DIN_Clock:	Source of digital input FIFO clock. Valid values are DM6430HR_DI_FIFO_CLK_USER_TC0, DM6430HR_DI_FIFO_CLK_USER_TC1, DM6430HR_DI_FIFO_CLK_AD_WRITE_FIFO, DM6430HR_DI_FIFO_CLK_EXTERNAL_PACER, and DM6430HR_DI_FIFO_CLK_EXTERNAL_TRIG.

Return Value:

0:	Success.
-1	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	DIN_Clock is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Digital Input FIFO Configuration Register at base I/O address + 10
 */

io_request.reg = r_DIN_CONFIG_6430;

/*
 * Only change bits 0 through 2 in Configuration Register
 */

io_request.mask = 0xFFF8;

/*
 * Set source for digital input FIFO clock to the output of User Timer/Counter 0
 */

io_request.value = DM6430HR_DI_FIFO_CLK_USER_TC0;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

DeInstallDMA6430

int DeInstallDMA6430(int descriptor, enum DM6430HR_DMA DMAChannel);

Description:

Configure the specified DMA circuit on a board so that DMA can no longer be performed on it.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
DMAChannel:	DMA circuit to configure. Valid values are DM6430HR_DMA1 and DM6430HR_DMA2.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	DMAChannel is not valid.
EINVAL	No DMA channel was ever allocated to DMAChannel.

IOCTL Interface:

```
int rc;
struct DM6430HR_DI io_request;

/*
 * Operate on board's first DMA circuit
 */

io_request.dma = DM6430HR_DMA1;

/*
 * DMA can no longer be performed on the circuit
 */

io_request.action = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_INSTALL, &io_request);
```

DINClockEnable6430

```
int DINClockEnable6430(int descriptor, int Enable);
```

Description:

Enable or disable a board's digital input FIFO clock.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Enable:	Indicates whether or not to enable the digital input FIFO clock. A value of 0 means disable the clock. A nonzero value means enable the clock.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Digital Input FIFO Configuration Register at base I/O address + 10
 */

io_request.reg = r_DIN_CONFIG_6430;

/*
 * Only change bit 3 in Configuration Register
 */

io_request.mask = 0xFFF7;

/*
 * Disable digital input FIFO clock
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

DIOClearChip6430

---

int DIOClearChip6430(int descriptor);

Description:

Clear a board's digital I/O chip.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

This function makes use of several ioctl() requests.

DIOClearIrq6430

---

int DIOClearIrq6430(int descriptor);

Description:

Clear a board's digital I/O IRQ status flag.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

This function makes use of several ioctl() requests.

DIOEnableIrq6430

---

int DIOEnableIrq6430(int descriptor, int Enable);

Description:

Enable or disable a board's digital interrupts.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Enable: Flag indicating how digital interrupts should be set. A value of 0 means disable digital interrupts. A nonzero value means enable digital interrupts.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO8 io_request;

/*
 * Write to Digital Mode Register at base I/O address + 30
 */

io_request.reg = r_DIO_MODE_6430;

/*
 * Only change bit 4 in Mode Register
 */

io_request.mask = 0xEF;

/*
 * Enable digital interrupts
 */

io_request.value = (1 << 4);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTB, &io_request);
```

DIOIsChipIrq6430

---

int DIOIsChipIrq6430(int descriptor, int *interrupt_generated_p);

Description:

Determine whether or not a board has generated a digital I/O interrupt.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

interrupt_generated_p: Address where interrupt generated flag should be stored. If the board has generated a digital I/O interrupt, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from the Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
if (rc != -1) {

   /*
    * If bit 6 is set in Status Register, an interrupt occurred
    */

   if (io_request.value & 0x40) {
      fprintf(stdout, "Digital I/O interrupt generated.\n");
   }
}
```

DIOIsChipIRQEnabled6430

---

int DIOIsChipIRQEnabled6430(int descriptor, int *irq_enabled_p);

Description:

Determine whether or not digital interrupts are enabled for a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

irq_enabled_p: Address where IRQ enabled flag should be stored. If digital interrupts are enabled, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from the Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
if (rc != -1) {

   /*
    * If bit 4 is cleared in Status Register, digital I/O interrupts are disabled
    */

   if ((io_request.value & 0x10) == 0) {
     fprintf(stdout, "Digital I/O interrupts disabled.\n");
   }
}
```

DIOIsChipIRQEventMode6430

int DIOIsChipIRQEventMode6430(int descriptor, int *irq_event_p);

Description:

Determine whether or not a board's digital interrupt mode is set to event.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
irq_event_p:	Address where IRQ event mode flag should be stored. If digital interrupts are in event mode, a nonzero value will be stored here. Otherwise, 0 will be stored here (meaning digital interrupts are in match mode).

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from the Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
if (rc != -1) {

   /*
    * If bit 3 is cleared in Status Register
    * Then
    *     Interrupt mode is event
    * Else
    *     Interrupt mode is match
    */

   if ((io_request.value & 0x08) == 0) {
      fprintf(stdout, "Digital I/O interrupts in event mode.\n");
   } else {
      fprintf(stdout, "Digital I/O interrupts in match mode.\n");
   }
}
```

int DIOIsChipPort1Output6430(int descriptor, int *port1_output_p);

Description:

Determine whether or not a board's digital port 1 is set to output.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
port1_output_p:	Address where port 1 output flag should be stored. If port 1 is set to output, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from the Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
if (rc != -1) {

   /*
    * If bit 2 is set in Status Register
    * Then
    *     Port 1 is output
    * Else
    *     Port 1 is input
    */
```

```
   if (io_request.value & 0x04) {
      fprintf(stdout, "Port 1 set to output.\n");
   } else {
      fprintf(stdout, "Port 1 set to input.\n");
   }
}
```

DIOIsChipStrobe6430

int DIOIsChipStrobe6430(int descriptor, int *strobe_occurred_p);

Description:

Determine whether or not data has been strobed into digital I/O port 0.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
strobe_occurred_p:	Address where strobe event flag should be stored. If data was strobed into port 0, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from the Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
if (rc != -1) {
```

```
   /*
    * If bit 7 is set in Status Register
    * Then
    *     Data was strobed into port 0
    * Else
    *     No data strobed
    */

   if (io_request.value & 0x80) {
     fprintf(stdout, "Data strobed into digital I/O port 0.\n");
   } else {
     fprintf(stdout, "No data strobed into digital I/O port 0.\n");
   }
}
```

DIOIsChipSystemClock6430

---

int DIOIsChipSystemClock6430(int descriptor, int *system_clock_p);

Description:

Determine whether or not the 8 MHz system clock is driving digital I/O sampling.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
system_clock_p:	Address where system clock flag should be stored. If the 8 MHz system clock is driving digital sampling, a nonzero value will be stored here. Otherwise, 0 will be stored here (meaning that the User Timer/Counter is driving sampling).

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from the Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;
```

```
/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
if (rc != -1) {

   /*
    * If bit 5 is cleared in Status Register
    * Then
    *     8 MHz system clock in use
    * Else
    *     User Timer/Counter in use
    */

   if ((io_request.value & 0x20) == 0) {
      fprintf(stdout, "8 MHz system clock driving digital I/O sampling.\n");
   } else {
      fprintf(stdout, "User Timer/Counter driving digital I/O sampling.\n");
   }
}
```

DIOLoadCompare6430

int DIOLoadCompare6430(int descriptor, u_int8_t Compare);

Description:

Load the Compare Register for a board's digital I/O port 0.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Compare:	The bit pattern to be matched.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.

IOCTL Interface:

This function makes use of several ioctl() requests.

DIOLoadMask6430

int DIOLoadMask6430(int descriptor, u_int8_t Mask);

Description:

Load the Mask Register for a board's digital I/O port 0.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Mask: The bit mask to be loaded.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

This function makes use of several ioctl() requests.

DIORead6430

int DIORead6430(int descriptor, enum DM6430HR_DIO Port, u_int8_t *digital_data_p);

Description:

Read 8 bits of data from board's specified digital I/O port.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Port: Indicates which digital I/O port to read. Valid values are DM6430HR_DIO0 and DM6430HR_DIO1.

digital_data_p: Address where data read should be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

EINVAL Port is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from Digital I/O Port 1 Register at base I/O address + 26
 */

io_request.reg = r_DIO_PORT_1_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
```

DIOReadCompareRegister6430

---

int DIOReadCompareRegister6430(int descriptor, u_int8_t *register_value_p);

Description:

Read the contents of a board's digital I/O Compare Register.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
register_value_p:	Address where register contents should be stored.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

This function makes use of several ioctl() requests.

DIOReadStatus6430

int DIOReadStatus6430(int descriptor, u_int8_t *status_p);

Description:

Read the contents of a board's Digital IRQ/Strobe Status register. Other library functions make use of this routine to perform their work.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

status_p: Address where digital I/O status register contents should be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from Digital IRQ/Strobe Status Register at base I/O address + 30
 */

io_request.reg = r_DIO_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the byte read.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
```

DIOSelectClock6430

int DIOSelectClock6430(int descriptor, enum DM6430HR_CLK_SEL Clock);

Description:

Select the sample clock source for a board's digital I/O chip.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Clock: Indicates the clock source. Valid values are DM6430HR_CLOCK_TC and DM6430HR_USER_TC.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL Clock is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO8 io_request;

/*
 * Write to Digital Mode Register at base I/O address + 30
 */

io_request.reg = r_DIO_MODE_6430;

/*
 * Only change bit 5 in Mode Register
 */

io_request.mask = 0xDF;

/*
 * Set digital I/O sample clock source to User Timer/Counter 1
 */

io_request.value = (DM6430HR_USER_TC << 5);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTB, &io_request);
```

DIOSelectIrqMode6430

int DIOSelectIrqMode6430(int descriptor, enum DM6430HR_DIO_IRQ IrqMode);

Description:

Set the advanced digital interrupt mode for a board's digital I/O chip port 0.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

IrqMode: Indicates the digital interrupt mode. Valid values are DM6430HR_DIO_IRQ_EVENT and DM6430HR_DIO_IRQ_MATCH .

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL IrqMode is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO8 io_request;

/*
 * Write to Digital Mode Register at base I/O address + 30
 */

io_request.reg = r_DIO_MODE_6430;

/*
 * Only change bit 3 in Mode Register
 */

io_request.mask = 0xF7;

/*
 * Set digital I/O interrupt mode to Event Mode
 */

io_request.value = (DM6430HR_DIO_IRQ_EVENT << 3);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTB, &io_request);
```

DIOSelectRegister6430

---

int DIOSelectRegister6430(int descriptor, enum DM6430HR_REG_SEL Select);

Description:

Set the mode of a board's digital I/O port 0 Direction/Mask/Compare Register located at base I/O address + 28. Other library functions make use of this routine to perform their work.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Select: Which mode to configure. Valid values are DM6430HR_REG_CLEAR, DM6430HR_REG_DIR, DM6430HR_REG_MASK, and DM6430HR_REG_CMP.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL Select is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO8 io_request;

/*
 * Write to Digital Mode Register at base I/O address + 30
 */

io_request.reg = r_DIO_MODE_6430;

/*
 * Only change bits 0 and 1 in Mode Register
 */

io_request.mask = 0xFC;

/*
 * Put digital I/O port 0 Direction/Mask/Compare Register into Clear Mode.  A subsequent read
 * from this register will clear the digital IRQ status flag whereas a subsequent write to the this
 * register will clear the digital I/O chip.
 */

io_request.value = DM6430HR_REG_CLEAR;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTB, &io_request);
```

DIOSetPort0Direction6430

int DIOSetPort0Direction6430(int descriptor, u_int8_t Direction);

Description:

Set the digital I/O port 0 bit direction (input or output) on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Direction: Bit mask indicating bit direction for port 0 bits. A 1 in the mask means set that bit to output. A 0 in the mask means set that bit to input.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

This function makes use of several ioctl() requests.

DIOSetPort1Direction6430

---

int DIOSetPort1Direction6430(int descriptor, int Direction);

Description:

Set the digital I/O port 1 bit direction (input or output) on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Direction: Flag indicating bit direction. A value of 0 means set port 1 bits to input. A nonzero value means set port 1 bits to output.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO8 io_request;

/*
 * Write to Digital Mode Register at base I/O address + 30
 */

io_request.reg = r_DIO_MODE_6430;
```

```
/*
 * Only change bit 2 in Mode Register
 */

io_request.mask = 0xFB;

/*
 * Set digital I/O port 1 bit direction to output.  All port bits are set to this direction.
 */

io_request.value = (1 << 2);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTB, &io_request);
```

DIOWrite6430

---

int DIOWrite6430(int descriptor, enum DM6430HR_DIO Port, u_int8_t Data);

Description:

Write data to a board's selected digital I/O port.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Port:	The port to write to. Valid values are DM6430HR_DIO0 and DM6430HR_DIO1.
Data:	The data to write.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	Port is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Write to digital I/O port 0
 */

io_request.reg = r_DIO_PORT_0_6430;
```

```
/*
 * Write the value 0x44 (68 decimal)
 */

io_request.value = 0x44;

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTB, &io_request);
```

DisableIRQ6430

int DisableIRQ6430(int descriptor, enum DM6430HR_INT IRQChannel);

Description:

Disable the specified interrupt circuit on a board.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
IRQChannel:	Interrupt circuit to disable. Valid values are DM6430HR_INT1 and DM6430HR_INT2.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	IRQChannel is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_IE io_request;

/*
 * Target of operation is second interrupt circuit
 */

io_request.intr = DM6430HR_INT2;

/*
 * Disable the interrupt circuit
 */

io_request.action = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_IRQ_ENABLE, &io_request);
```

DoneTimer6430

int DoneTimer6430(int descriptor);

Description:

Initialize a board's user timer/counter counter 0 and counter 1 for high speed to ensure immediate load. This function puts these two counters into mode 2.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure. Please see the descriptions of the ClockDivisor6430(), ClockMode6430(), and SelectTimerCounter6430() functions or the ioctl(2) man page for information on possible values errno may have in this case.

IOCTL Interface:

This function makes use of several ioctl() requests.

EnableIRQ6430

int EnableIRQ6430(int descriptor, enum DM6430HR_INT IRQChannel);

Description:

Enable the specified interrupt circuit on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

IRQChannel: Interrupt circuit to enable. Valid values are DM6430HR_INT1 and DM6430HR_INT2.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL IRQChannel is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_IE io_request;

/*
 * Target of operation is first interrupt circuit
 */

io_request.intr = DM6430HR_INT1;

/*
 * Enable the interrupt circuit
 */

io_request.action = 1;

rc = ioctl(descriptor, DM6430HR_IOCTL_IRQ_ENABLE, &io_request);
```

EnableTables6430

---

int EnableTables6430(int descriptor, int Enable_AD_Table, int Enable_Digital_Table);

Description:

Enable or disable the A/D and digital tables in the channel/gain scan memory on a board.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Enable_AD_Table:	Flag to indicate whether the A/D table should be enabled. A value of 0 means disable the A/D table. A nonzero value means enable the A/D table.
Enable_Digital_Table:	Flag to indicate whether the digital table should be enabled. A value of 0 means disable the digital table. A nonzero value means enable the digital table.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for write access.
EOPNOTSUPP	The digital table is to be enabled but the A/D table is to be disabled.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Control Register at base I/O address + 2
 */

io_request.reg = r_CONTROL_6430;

/*
 * Only change bits 2 and 3 in Control Register
 */

io_request.mask = 0xFFF3;

/*
 * Enable just the A/D table
 *
 * To disable both tables, set io_request.value to 0.
 * To enable both tables, set io_request.value to (0x3 << 2)
 */

io_request.value = (1 << 2);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

GetAutoincData6430

```
int GetAutoincData6430(
   int descriptor,
   enum DM6430HR_STR_Regs from_register,
   enum DM6430HR_STR_TYPE type,
   void *buffer_p,
   size_t element_num
);
```

Description:

Initiate a streaming read from a board. Once can specify the board register to read from, what size data is to be transferred, and how many data elements to transfer.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
from_register:	Register from which the data should be read. Valid values are rSTR_AD_6430 and rSTR_DIN_FIFO_6430.

type: Type/size of element to be transferred. Valid values are DM6430HR_STR_TYPE_BYTE and DM6430HR_STR_TYPE_WORD.

buffer_p: Address of buffer in which to place the data read.

element_num: How many data elements of type "type" should be read.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for read access.
EFAULT	buffer_p is not a valid user address.
EINVAL	from_register is not valid.
EINVAL	type is not valid.
EOPNOTSUPP	from_register is rSTR_AD_6430 and type is DM6430HR_STR_TYPE_BYTE.
EOPNOTSUPP	from_register is rSTR_DIN_FIFO_6430 and type is DM6430HR_STR_TYPE_WORD.

IOCTL Interface:

```
int rc;
struct DM6430HR_GID io_request;
int16_t ad_buffer[600];
uint8_t digital_buffer[512];

/*
 * Read from A/D input FIFO
 */

io_request.port = rSTR_AD_6430;

/*
 * Transfer 16-bit values
 */

io_request.type = DM6430HR_STR_TYPE_WORD;

/*
 * Transfer data into ad_buffer[] array
 */

io_request.buf = (void *) &(ad_buffer[0]);
```

```
/*
 * Transfer 600 16-bit values
 */

io_request.times = 600;

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_GETINC, &io_request);

/*
 * Read from digital port 0 input FIFO
 */

io_request.port = rSTR_DIN_FIFO_6430;

/*
 * Transfer 8-bit values
 */

io_request.type = DM6430HR_STR_TYPE_BYTE;

/*
 * Transfer data into digital_buffer[] array
 */

io_request.buf = (void *) &(digital_buffer[0]);

/*
 * Transfer 512 8-bit values
 */

io_request.times = 512;

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_GETINC, &io_request);
```

GetDmaData6430

```
int GetDmaData6430(
    int descriptor,
    void *dma_buffer_p,
    enum DM6430HR_DMA DMAChannel,
    size_t length,
    size_t offset,
    size_t *bytes_transferred_p
);
```

Description:

Copy data from specified DMA circuit's DMA buffer into user buffer.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
dma_buffer_p:	Address of user buffer.
DMAChannel:	DMA circuit to operate on. Valid values are DM6430HR_DMA1 and DM6430HR_DMA2.
length:	Number of bytes to transfer.
offset:	Offset in bytes from beginning of driver's DMA buffer.
bytes_transferred_p:	Address where actual number of bytes transferred will be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for read access.
EFAULT	dma_buffer_p is not a valid user address.
EFAULT	dma_buffer_p is not large enough to hold the data.
EINVAL	DMAChannel is not valid.
EINVAL	No DMA channel was ever allocated to DMAChannel.
EINVAL	No DMA buffer was ever allocated to DMAChannel.
EINVAL	(length + offset) lies beyond the end of the driver's DMA buffer.

IOCTL Interface:

```
int rc;
struct DM6430HR_GDD io_request;
int16_t user_buffer[8192];

/*
 * Read from DMA buffer on second DMA circuit
 */

io_request.dma = DM6430HR_DMA2;

/*
 * Transfer data into user_buffer[] array
 */

io_request.buf = (void *) &(user_buffer[0]);
```

```
/*
 * Transfer 8192 16-bit values (16384 8-bit values)
 */

io_request.length = 16384;

/*
 * Read from beginning of driver's DMA buffer
 */

io_request.offset = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_GETDATA, &io_request);
```

GetIRQCounter6430

```
int GetIRQCounter6430(
   int descriptor,
   enum DM6430HR_INT IRQChannel,
   unsigned long *counter_value_p
);
```

Description:

Get the number of interrupts that have occurred on a board's specified interrupt circuit.

Data returned from this function is interpreted differently depending upon usage of the force argument on the insmod command. If you specify a nonzero value for the force argument, the value returned represents the number of interrupts that occurred since the driver module was loaded. If you specify a zero value for the force argument or do not use force at all, the value returned represents the number of interrupts that occurred since the device file was opened.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
IRQChannel:	Interrupt circuit to read counter value from. Valid values are DM6430HR_INT1 and DM6430HR_INT2.
counter_value_p:	Address where counter value should be stored.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.
	EINVAL	IRQChannel is not valid.
	EINVAL	No IRQ was ever allocated to IRQChannel.

IOCTL Interface:

```
int rc;
struct DM6430HR_GIC io_request;

/*
 * Target of operation is first interrupt circuit
 */

io_request.intr = DM6430HR_INT1;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable counter contains the interrupt count.
 */

io_request.counter = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_GET_IRQ_COUNTER, &io_request);
if (rc != -1) {
   fprintf(stdout, "Interrupt count: %ld.\n", io_request.counter);
}
```

InitBoard6430

---

int InitBoard6430(int descriptor);

Description:

Initialize a board. This will 1) clear the board, 2) clear the A/D DMA done flag, 3) clear the channel/gain table, and 4) clear the A/D input FIFO.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

This function makes use of several ioctl() requests.

InstallCallbackIRQHandler6430

```
int InstallCallbackIRQHandler6430(
   int descriptor,
   void (*callback)(void),
   enum DM6430HR_INT IRQChannel
);
```

Description:

Install a function which will be called whenever an interrupt occurs and the driver sends a signal to the process to indicate that the interrupt happened.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
callback:	Address of callback function.
IRQChannel:	Board interrupt circuit that signal should be attached to.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	callback is NULL.
EINVAL	IRQChannel is not valid.
ENOMEM	Library callback descriptor memory could not be allocated.

Please see the sigaction(2) man page, the sigprocmask(2) man page, or the ioctl(2) man page for information on other possible values errno may have in this case.

IOCTL Interface:

This function makes use of several ioctl() requests.

InstallDMA6430

```
int InstallDMA6430(int descriptor, enum DM6430HR_DMA DMAChannel);
```

Description:

Configure the specified DMA circuit on a board to be able to perform DMA.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
DMAChannel:	DMA circuit to configure. Valid values are DM6430HR_DMA1 and DM6430HR_DMA2.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	DMAChannel is not valid.
EINVAL	No DMA channel was ever allocated to DMAChannel.
ENOMEM	DMA buffer memory allocation failed.

IOCTL Interface:

```
int rc;
struct DM6430HR_DI io_request;

/*
 * Target of operation is second DMA circuit
 */

io_request.dma = DM6430HR_DMA2

/*
 * Enable DMA on the circuit
 */

io_request.action = 1;

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_INSTALL, &io_request);
```

IsAboutTrigger6430

---

int IsAboutTrigger6430(int descriptor, int *ad_about_trigger_p);

Description:

Determine whether or not a board's A/D about trigger has occurred.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_about_trigger_p:	Address where A/D about trigger flag should be stored. If A/D about trigger has occurred, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 8 is set in Status Register, then about trigger has occurred
    *
    * If bit 8 is cleared, then about trigger has not occurred
    */

   if (io_request.value & 0x0100) {
     fprintf(stdout, "About trigger occurred.\n");
   }
}
```

int IsADConverting6430(int descriptor, int *ad_converting_p);

Description:

Determine whether or not a board's A/D converter is converting.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_converting_p:	Address where A/D converting flag should be stored. If A/D conversion is occurring, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 3 is cleared in Status Register, then A/D converter is converting
    *
    * If bit 3 is set, then A/D converter is not converting
    */
```

```
   if ((io_request.value & 0x0008) == 0) {
      fprintf(stdout, "A/D converter is still converting.\n");
   }
}
```

IsADDMADone6430

int IsADDMADone6430(int descriptor, int *ad_dma_done_p);

Description:

Determine whether or not a board's A/D DMA transfer is complete.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_dma_done_p	Address where A/D DMA done flag should be stored. If A/D DMA is finished, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {
```

```
   /*
    * If bit 4 is set in Status Register, then A/D DMA is done
    *
    * If bit 4 is cleared, then A/D DMA is not done
    */

   if (io_request.value & 0x0010) {
     fprintf(stdout, "A/D DMA completed.\n");
   }
}
```

IsADFIFOEmpty6430

---

int IsADFIFOEmpty6430(int descriptor, int *ad_fifo_empty_p);

Description:

Determine whether or not a board's A/D FIFO is empty.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_fifo_empty_p:	Address where FIFO empty flag should be stored. If the A/D FIFO is empty, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;
```

```
rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 0 is cleared in Status Register, then A/D FIFO is empty
    *
    * If bit 0 is set, then A/D FIFO is not empty
    */

   if ((io_request.value & 0x0001) == 0) {
     fprintf(stdout, "A/D FIFO empty.\n");
   }
}
```

IsADFIFOFull6430

int IsADFIFOFull6430(int descriptor, int *ad_fifo_full_p);

Description:

Determine whether or not a board's A/D FIFO is full.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_fifo_empty_p:	Address where FIFO full flag should be stored. If the A/D FIFO is full, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;
```

```
/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 1 is set in Status Register, then A/D FIFO is not full
    *
    * If bit 1 is cleared, then A/D FIFO is full
    */

   if (io_request.value & 0x0002) {
     fprintf(stdout, "A/D FIFO not full.\n");
   }
}
```

IsADHalted6430

int IsADHalted6430(int descriptor, int *ad_halted_p);

Description:

Determine whether or not a board's A/D conversion has been stopped because the sample buffer is full.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_halted_p:	Address where A/D halted flag should be stored. If A/D conversion has been stopped, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;
```

```
/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 2 is cleared in Status Register, then A/D conversion has not been stopped
    *
    * If bit 2 is set, then A/D conversion has been stopped
    */

   if ((io_request.value & 0x0004) == 0) {
      fprintf(stdout, "A/D conversion not halted due to sample buffer being full.\n");
   }
}
```

IsBurstClockOn6430

---

int IsBurstClockOn6430(int descriptor, int *ad_burst_clock_on_p);

Description:

Determine whether or not a board's A/D burst clock gate is on.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_burst_clock_on_p:	Address where A/D burst clock flag should be stored. If A/D burst clock gate is on, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 6 is set in Status Register, then burst gate is on
    *
    * If bit 6 is cleared, then burst gate is off
    */

   if (io_request.value & 0x0040) {
     fprintf(stdout, "Burst gate is on.\n");
   }
}
```

IsDigitalIRQ6430

```
int IsDigitalIRQ6430(int descriptor, int *digital_interrupt_p);
```

Description:

Determine whether or not an advanced digital mode interrupt has occurred on a board.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
digital_interrupt_p:	Address where digital interrupt flag should be stored. If an advanced digital interrupt has occurred, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 9 is cleared in Status Register, then no digital interrupt occurred
    *
    * If bit 9 is set, then digital interrupt occurred
    */

   if ((io_request.value & 0x0200) == 0) {
      fprintf(stdout, "Digital interrupt has not occurred.\n");
   }
}
```

IsDINFIFOEmpty6430

int IsDINFIFOEmpty6430(int descriptor, int *digital_fifo_empty_p);

Description:

Determine whether or not a board's digital input FIFO is empty.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
digital_fifo_empty_p:	Address where digital FIFO empty flag should be stored. If the digital FIFO is empty, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 10 is set in Status Register, then digital input FIFO is not empty
    *
    * If bit 10 is cleared, then digital input FIFO is empty
    */

   if (io_request.value & 0x0400) {
     fprintf(stdout, "Digital input FIFO is not empty.\n");
   }
}
```

int IsDINFIFOFull6430(int descriptor, int *digital_fifo_full_p);

Description:

Determine whether or not a board's digital input FIFO is full.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
digital_fifo_full_p:	Address where digital FIFO full flag should be stored. If the digital FIFO is full, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 12 is cleared in Status Register, then digital input FIFO is full
    *
    * If bit 12 is set, then digital input FIFO is not full
    */
```

```
    if ((io_request.value & 0x1000) == 0) {
      fprintf(stdout, "Digital input FIFO is full.\n");
    }
}
```

IsDINFIFOHalf6430

```
int IsDINFIFOHalf6430(int descriptor, int *digital_fifo_half_full_p);
```

Description:

Determine whether or not a board's digital input FIFO is half full.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
digital_fifo_half_full_p:	Address where digital FIFO half full flag should be stored. If the digital FIFO is half full, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {
```

```
   /*
    * If bit 11 is set in Status Register, then digital input FIFO is not half full
    *
    * If bit 11 is cleared, then digital input FIFO is half full
    */

   if (io_request.value & 0x0800) {
     fprintf(stdout, "Digital input FIFO is not half full.\n");
   }
}
```

IsFirstADDMADone6430

int IsFirstADDMADone6430(int descriptor, int *ad_first_dma_done_p);

Description:

Determine whether or not a board's A/D first DMA transfer is complete when in dual channel DMA mode.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_first dma_done_p:	Address where A/D first DMA done flag should be stored. If A/D first DMA is finished, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */
```

```
io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 5 is cleared in Status Register, then first DMA is not done
    *
    * If bit 5 is set, then first DMA is done
    */

   if ((io_request.value & 0x0020) == 0) {
     fprintf(stdout, "First DMA not done.\n");
   }
}
```

IsPacerClockOn6430

---

int IsPacerClockOn6430(int descriptor, int *ad_pacer_clock_on_p);

Description:

Determine whether or not a board's A/D pacer clock gate is on.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
ad_pacer_clock_on_p:	Address where A/D pacer clock flag should be stored. If A/D pacer clock gate is on, a nonzero value will be stored here. Otherwise, 0 will be stored here.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */

io_request.reg = r_STATUS_6430;
```

```
/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
if (rc != -1) {

   /*
    * If bit 7 is set in Status Register, then A/D pacer clock gate is on
    *
    * If bit 7 is cleared, then pacer clock gate is off
    */

   if (io_request.value & 0x0080) {
      fprintf(stdout, "A/D pacer clock gate is on.\n");
   }
}
```

LoadADSampleCounter6430

---

int LoadADSampleCounter6430(int descriptor, u_int16_t NumOfSamples);

Description:

Load a board's analog to digital sample counter.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
NumOfSamples:	Number of samples to take.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

This function makes use of several ioctl() requests.

LoadADTable6430

int LoadADTable6430(int descriptor, u_int16_t ADEntries, ADTableRow *ADTable_p);

Description:

Load a board's A/D table with the given number of entries.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

ADEntries: Number of entries in A/D table.

ADTable_p: Address of memory containing A/D table to send to board.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL ADEntries is 0.

EINVAL ADEntries is greater than 1024.

IOCTL Interface:

This function makes use of several ioctl() requests.

LoadControlRegister6430

int LoadControlRegister6430(int descriptor, u_int16_t value);

Description:

Load a value into a board's Control Register.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

value: Data to write into Control Register.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Write to Control Register at base I/O address + 2
 */

io_request.reg = r_CONTROL_6430;

/*
 * Set first DMA circuit to use DMA channel 5
 */

io_request.value = (1 << 12);

/*
 * Set second DMA circuit to use DMA channel 7
 */

io_request.value |= (3 << 14);

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

LoadDAC26430

```
int LoadDAC26430(int descriptor, int16_t Data);
```

Description:

Load a 16-bit two's complement value into a board's DAC2 Output Register.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Data: Value to write into register.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;
```

```
/*
 * Write to DAC2 Output Register at base I/O address + 14
 */

io_request.reg = r_DAC2_6430;

/*
 * Write -1 (0xFFFF in two's complement) to D/A converter
 */

io_request.value = 0xFFFF;

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

LoadDAC6430

---

int LoadDAC6430(int descriptor, int16_t Data);

Description:

Load a 16-bit two's complement value into a board's DAC1 Output Register.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Data: Value to write into register.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;
/*
 * Write to DAC1 Output Register at base I/O address + 12
 */

io_request.reg = r_DAC1_6430;

/*
 * Write -1 (0xFFFF in two's complement) to D/A converter
 */

io_request.value = 0xFFFF;

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

LoadDigitalTable6430

int LoadDigitalTable6430(int descriptor, int entries, u_int8_t *table_p);

Description:

Load a board's digital table with the given number of entries.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
entries:	Number of entries in digital table.
table_p:	Address of memory containing digital table to send to board. This memory is an array of unsigned bytes.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	entries is 0.
	EINVAL	entries is greater than 1024.

IOCTL Interface:

This function makes use of several ioctl() requests.

LoadDINConfigRegister6430

int LoadDINConfigRegister6430(int descriptor, u_int16_t value);

Description:

Load a 16-bit value into a board's Digital Input FIFO Configuration Register.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
value:	Value to write into register.

Return Value:

0:	Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Write to Digital Input FIFO Configuration Register at base I/O address + 10
 */

io_request.reg = r_DIN_CONFIG_6430;

/*
 * Set digital input FIFO clock source to output of user timer/counter 1
 */

io_request.value = 0x0001;

/*
 * Enable digital input FIFO clock
 */

io_request.value |= (1 << 3);

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

LoadIRQRegister6430

```
int LoadIRQRegister6430(int descriptor, u_int16_t value);
```

Description:

Load a 16 bit value into a board's Interrupt Register.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

value: Value to load into Interrupt Register.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Write to Interrupt Register at base I/O address + 8
 */

io_request.reg = r_IRQ_6430

/*
 * Set source of interrupts on first circuit to be write to digital input FIFO
 */

io_request.value = 0x000F;

/*
 * Use IRQ5 for first interrupt circuit
 */

io_request.value |= (1 << 6);

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

LoadTriggerRegister6430

```
int LoadTriggerRegister6430(int descriptor, u_int16_t value);
```

Description:

Load a 16-bit value into a board's Trigger Mode Register.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

value: Value to write into Trigger Mode Register.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
```

```
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Pacer Clock controls A/D conversion
 */

io_request.value = 0x0001;

/*
 * Start Pacer Clock when digital interrupt received
 */

io_request.value |= (1 << 3);

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

OpenBoard6430

---

int OpenBoard6430(int DeviceNumber);

Description:

Open a DM6430 device file.

Parameters:

DeviceNumber:	Minor number of board device file.

Return Value:

>=0:	Success. The integer returned is the file descriptor from open() system call.
-1:	Failure. Please see the open(2) man page for information on possible values errno may have in this case.

IOCTL Interface:

None.

ReadADData6430

---

int ReadADData6430(int descriptor, int16_t *ad_data_p);

Description:

Read 16 bits from a board's analog to digital FIFO.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

ad_data_p: Address where data read should be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from A/D Data FIFO Register at base I/O address + 4
 */

io_request.reg = r_AD_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the A/D data.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
```

ReadChannelGainDataStore6430

int ReadChannelGainDataStore6430(int descriptor, u_int16_t *cgds_data_p);

Description:

Read a board's channel/gain data word. This function assumes the caller knows whether or not the channel/gain data store has been enabled since there is no way to query the board for this status.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

cgds_data_p: Address where data read should be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from A/D Data FIFO Register at base I/O address + 4
 */

io_request.reg = r_AD_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the channel/gain data.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
```

ReadDINFIFO6430

---

int ReadDINFIFO6430(int descriptor, u_int8_t *digital_data_p);

Description:

Read 8 bits of data from the digital input FIFO.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

digital_data_p: Address where data read should be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO8 io_request;

/*
 * Read from Digital Input FIFO Register at base I/O address + 10
 */

io_request.reg = r_DIN_FIFO_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the digital data.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INB, &io_request);
```

ReadStatus6430

```
int ReadStatus6430(int descriptor, u_int16_t *status_p);
```

Description:

Read a board's Status Register. Other library functions make use of this routine to perform their work.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

status_p: Address where status should be stored.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Status Register at base I/O address + 2
 */
```

```
io_request.reg = r_STATUS_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the register contents.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
```

ReadTimerCounter6430

```
int ReadTimerCounter6430(
   int descriptor,
   enum DM6430HR_CLK_SEL Timer,
   enum DM6430HR_CLK Clock,
   u_int16_t *counter_value_p
);
```

Description:

Read the 16 bit contents of the desired timer/counter. The read is done as two 8 bit reads: least significant byte then most significant byte.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Timer:	Indicates which timer/counter to use. Valid values are DM6430HR_CLOCK_TC and DM6430HR_USER_TC.
Clock:	Indicates which counter to use. Valid values are DM6430HR_CLK0, DM6430HR_CLK1, and DM6430HR_CLK2.
counter_value_p:	Address where timer contents should be stored.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	Timer is not valid.
	EINVAL	Clock is not valid.

IOCTL Interface:

This function makes use of several ioctl() requests.

RemoveIRQHandler6430

---

int RemoveIRQHandler6430(int descriptor, enum DM6430HR_INT IRQChannel);

Description:

Uninstall the function which was previously registered as an interrupt callback by InstallCallbackIRQHandler6430().

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

IRQChannel: Board interrupt circuit that signal should be detached from.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL IRQChannel is not valid.

EINVAL No IRQ was ever allocated to IRQChannel.

IOCTL Interface:

This function makes use of a single ioctl() call. However in addition to this ioctl() call, several other system calls are used to reset process signal handling state; a description is beyond the scope of this document.

ResetChannelGainTable6430

---

int ResetChannelGainTable6430(int descriptor);

Description:

Reset a board's channel/gain table starting point to the beginning of the table.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

int rc;

rc = ioctl(descriptor, DM6430HR_IOCTL_CLEAR, DM6430_CL_RESET_GAIN);

SelectTimerCounter6430

---

int SelectTimerCounter6430(int descriptor, enum DM6430HR_CLK_SEL Select);

Description:

Select which timer/counter on a board will be accessed when a subsequent operation is performed on the registers located at base I/O address + 16 through base I/O address + 22. Other library functions make use of this routine to perform their work.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Select: Indicate which timer/counter will be accessed. Valid values are DM6430HR_CLOCK_TC and DM6430HR_USER_TC.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL Select is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Control Register at base I/O address + 2
 */

io_request.reg = r_CONTROL_6430;
```

```
/*
 * Only change bits 5 and 6 in Control Register
 */

io_request.mask = 0xFF9F;

/*
 * Select User Timer/Counter
 */

io_request.value = (1 << 5);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetBurstClock6430

int SetBurstClock6430(int descriptor, double BurstRate, double *actual_p);

Description:

Set a board's burst clock rate.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
BurstRate:	Burst clock rate desired.
actual_p:	Address where the actual programmed frequency should be stored. If this function fails, the actual frequency is not updated.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.

IOCTL Interface:

This function makes use of several ioctl() requests.

SetBurstTrigger6430

int SetBurstTrigger6430(int descriptor, enum DM6430HR_BURST_TRIG Burst_Trigger);

Description:

Select a board's burst mode trigger.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Burst_Trigger:	What triggers a burst. Valid values are DM6430HR_BURST_TRIG_SOFTWARE, DM6430HR_BURST_TRIG_PACER, DM6430HR_BURST_TRIG_EXTERNAL, and DM6430HR_BURST_TRIG_DIGITAL.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	Burst_Trigger is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bits 10 and 11 in Trigger Mode Register
 */

io_request.mask = 0xF3FF;

/*
 * Bursts triggered by external trigger
 */

io_request.value = (1 << 11);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

```
int SetChannelGain6430(
   int descriptor,
   enum DM6430HR_AIN Channel,
   enum DM6430HR_GAIN Gain,
   enum DM6430HR_SE Se_Diff
);
```

Description:

Load a board's channel/gain latch.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Channel:	A/D channel. Valid values are DM6430HR_AIN1, DM6430HR_AIN2, DM6430HR_AIN3, DM6430HR_AIN4, DM6430HR_AIN5, DM6430HR_AIN6, DM6430HR_AIN7, DM6430HR_AIN8, DM6430HR_AIN9, DM6430HR_AIN10, DM6430HR_AIN11, DM6430HR_AIN12, DM6430HR_AIN13, DM6430HR_AIN14, DM6430HR_AIN15, and DM6430HR_AIN16.
Gain:	A/D gain. Valid values are DM6430HR_GAINx1, DM6430HR_GAINx2, DM6430HR_GAINx4, and DM6430HR_GAINx8.
Se_Diff:	Select single-ended or differential mode. Valid values are DM6430HR_SE_SE and DM6430HR_SE_DIFF.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	Channel is not valid.
	EINVAL	Gain is not valid.
	EINVAL	Se_Diff is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Before loading channel/gain latch, bits 1 and 0 in Control Register at base
 * I/O address + 2 must be set to zeroes.  This is not shown here.
 */
```

```
/*
 * Write to Load Channel/Gain Latch Register at base I/O address + 4
 */

io_request.reg = r_CHANNEL_GAIN_6430;

/*
 * Target of operation is analog input channel 7
 */

io_request.value = 0x0006;

/*
 * Set x2 gain
 */

io_request |= (1 << 4);

/*
 * Set differential mode
 */

io_request |= (1 << 9);

rc = ioctl(descriptor, DM6430HR_IOCTL_OUTW, &io_request);
```

SetConversionSelect6430

---

int SetConversionSelect6430(int descriptor, enum DM6430HR_CONV Select);

Description:

Configure how a board's A/D conversion is done.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Select:	Indicates how A/D conversions are controlled. Valid values are DM6430HR_CONV_SOFT_TRIGGER, DM6430HR_CONV_PACER_CLOCK, DM6430HR_CONV_BURST_CLOCK, and DM6430HR_CONV_DIGITAL_INT.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.

EINVAL Select is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bits 0 and 1 in Trigger Mode Register
 */

io_request.mask = 0xFFFC;

/*
 * Pacer clock controls A/D conversion
 */

io_request.value = 0x0001;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetIRQ0Source6430

---

int SetIRQ0Source6430(int descriptor, enum DM6430HR_INTSRC IRQSource);

Description:

Select the interrupt source of the first interrupt circuit on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

IRQSource: Source of interrupt on first circuit. Valid values are
IRQS_AD_SAMPLE_CNT_6430,
IRQS_AD_START_CONVERT_6430,
IRQS_AD_END_CONVERT_6430,
IRQS_AD_WRITE_FIFO_6430,
IRQS_AD_FIFO_HALF_6430,
IRQS_AD_DMA_DONE_6430,
IRQS_RESET_GAIN_TABLE_6430,
IRQS_PAUSE_GAIN_TABLE_6430,
IRQS_EXT_PACER_CLOCK_6430,
IRQS_EXT_TRIGGER_6430,
IRQS_DIGITAL_6430,
IRQS_TC_COUNTER0_6430,

IRQS_TC_COUNTER0_INVERTED_6430,
IRQS_TC_COUNTER1_6430,
IRQS_DIO_FIFO_HALF_6430, and
IRQS_DIO_WRITE_FIFO_6430.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL IRQSource is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Interrupt Register at base I/O address + 8
 */

io_request.reg = r_IRQ_6430;

/*
 * Only change bits 0 through 4 in register
 */

io_request.mask = 0xFFE0;

/*
 * Set interrupt source to be A/D FIFO half full
 */

io_request.value = 0x0004;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetIRQ1Source6430

---

int SetIRQ1Source6430(int descriptor, enum DM6430HR_INTSRC IRQSource);

Description:

Select the interrupt source of the second interrupt circuit on a board.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

IRQSource: Source of interrupt on first circuit. Valid values are
IRQS_AD_SAMPLE_CNT_6430,
IRQS_AD_START_CONVERT_6430,
IRQS_AD_END_CONVERT_6430,
IRQS_AD_WRITE_FIFO_6430,
IRQS_AD_FIFO_HALF_6430,
IRQS_AD_DMA_DONE_6430,
IRQS_RESET_GAIN_TABLE_6430,
IRQS_PAUSE_GAIN_TABLE_6430,
IRQS_EXT_PACER_CLOCK_6430,
IRQS_EXT_TRIGGER_6430,
IRQS_DIGITAL_6430,
IRQS_TC_COUNTER0_6430,
IRQS_TC_COUNTER0_INVERTED_6430,
IRQS_TC_COUNTER1_6430,
IRQS_DIO_FIFO_HALF_6430, and
IRQS_DIO_WRITE_FIFO_6430.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL IRQSource is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Interrupt Register at base I/O address + 8
 */

io_request.reg = r_IRQ_6430;

/*
 * Only change bits 8 through 12 in register
 */

io_request.mask = 0xE0FF;

/*
 * Set interrupt source to be User Timer/Counter 0 countdown to zero
 */

io_request.value = (0xB << 8);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetPacerClock6430

int SetPacerClock6430(int descriptor, double clock, double *actual_p);

Description:

Set a board's pacer clock rate. This function decides whether to use a 16-bit or 32-bit clock depending upon the clock rate.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
clock:	Clock rate desired.
actual_p:	Address where the actual programmed frequency should be stored. If this function fails, the actual frequency is not updated.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	clock is greater than 8 MHz.
	EINVAL	clock is 0.0.
	EINVAL	clock is less than 0.0.

IOCTL Interface:

This function makes use of several ioctl() requests.

SetPacerClockSource6430

int SetPacerClockSource6430(int descriptor, enum DM6430HR_PACER_CLK Source);

Description:

Select the source of a board's pacer clock.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Source:	Pacer clock source. Valid values are DM6430HR_PACER_CLK_INTERNAL and DM6430HR_PACER_CLK_EXTERNAL.

Return Value:

0:	Success.
-1:	Failure with errno set as follows:
EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	Source is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bit 9 in register
 */

io_request.mask = 0xFDFF;

/*
 * Set internal pacer clock
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetPauseEnable6430

```
int SetPauseEnable6430(int descriptor, int Enable);
```

Description:

Enable or disable a board's A/D table pause bit.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Enable:	Flag to indicate whether the A/D table pause bit should set. A value of 0 means enable the pause bit. A nonzero value means disable the pause bit.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Control Register at base I/O address + 2
 */

io_request.reg = r_CONTROL_6430;

/*
 * Only change bit 8 in register
 */
io_request.mask = 0xFEFF;

/*
 * Activate pause bit in A/D table channel/gain scan memory
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetSampleCounterStop6430

---

int SetSampleCounterStop6430(int descriptor, int Disable);

Description:

Enable or disable a board's A/D Sample Counter Stop.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Disable: Flag to indicate whether the A/D sample counter should stop the pacer clock. A value of 0 means enable sample counter stop. A nonzero value means disable sample counter stop.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Control Register at base I/O address + 2
 */

io_request.reg = r_CONTROL_6430;

/*
 * Only change bit 7 in register
 */

io_request.mask = 0xFF7F;

/*
 * Disable A/D sample counter stop
 */

io_request.value = (1 << 7);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetStartTrigger6430

---

int SetStartTrigger6430(int descriptor, enum DM6430HR_START_TRIG Start_Trigger);

Description:

Configure how a board's pacer clock is started during A/D conversion.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Start_Trigger: What starts the pacer clock. Valid values are DM6430HR_START_TRIG_SOFTWARE, DM6430HR_START_TRIG_EXTERNAL, DM6430HR_START_TRIG_DIGITAL_INT, DM6430HR_START_TRIG_USER_TC1, and DM6430HR_START_TRIG_GATE.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	Start_Trigger is not valid.
EOPNOTSUPP	Start_Trigger is one of the three reserved bit patterns as defined in the hardware manual.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bits 2 through 4 in register
 */

io_request.mask = 0xFFE3;

/*
 * Start pacer clock when User Timer/Counter 1 counts down to zero
 */

io_request.value = (0x3 << 2);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetStopTrigger6430

---

int SetStopTrigger6430(int descriptor, enum DM6430HR_STOP_TRIG Stop_Trigger);

Description:

Configure how a board's pacer clock is stopped during A/D conversion.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Stop_Trigger: What stops the pacer clock. Valid values are
DM6430HR_STOP_TRIG_SOFTWARE,
DM6430HR_STOP_TRIG_EXTERNAL,
DM6430HR_STOP_TRIG_DIGITAL_INT,
DM6430HR_STOP_TRIG_SAMPLE_CNT,
DM6430HR_STOP_TRIG_ABOUT_SOFTWARE,
DM6430HR_STOP_TRIG_ABOUT_EXTERNAL,
DM6430HR_STOP_TRIG_ABOUT_DIGITAL, and
DM6430HR_STOP_TRIG_ABOUT_USER_TC1.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL Stop_Trigger is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bits 5 through 7 in register
 */

io_request.mask = 0xFF1F;

/*
 * Stop pacer clock by software trigger
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetTriggerPolarity6430

int SetTriggerPolarity6430(int descriptor, enum DM6430HR_POLAR Polarity);

Description:

Select which edge of an external pacer clock triggers a board's burst mode.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Polarity: Which external pacer clock edge triggers burst mode. Valid values are DM6430HR_POLAR_POSITIVE and DM6430HR_POLAR_NEGATIVE.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL Polarity is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bit 12 in register
 */

io_request.mask = 0xEFFF;

/*
 * Set external trigger to occur on negative edge
 */

io_request.value = (1 << 12);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetTriggerRepeat6430

int SetTriggerRepeat6430(int descriptor, enum DM6430HR_REPEAT Repeat);

Description:

Select whether or not a trigger initiates multiple A/D conversion cycles.

Parameters:

descriptor: File descriptor from OpenBoard6430() call.

Repeat: Indicates whether or not A/D conversion cycles repeat. Valid values are DM6430HR_REPEAT_SINGLE and DM6430HR_REPEAT_REPEAT.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES descriptor refers to a file that is open but not for write access.

EINVAL Repeat is not valid.

IOCTL Interface:

```
int rc;
struct DM6430HR_MIO16 io_request;

/*
 * Write to Trigger Mode Register at base I/O address + 6
 */

io_request.reg = r_TRIGGER_6430;

/*
 * Only change bit 13 in register
 */

io_request.mask = 0xDFFF;

/*
 * Enable trigger repeat
 */

io_request.value = (1 << 13);

rc = ioctl(descriptor, DM6430HR_IOCTL_MOUTW, &io_request);
```

SetUserClock6430

```
int SetUserClock6430(
   int descriptor,
   enum DM6430HR_CLK Timer,
   double InputRate,
   double OutputRate,
   double *actual_p
);
```

Description:

Set up a board's user clock.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
Timer:	Indicates which counter to use. Valid values are DM6430HR_CLK0, DM6430HR_CLK1, and DM6430HR_CLK2.
InputRate	Input frequency to specified counter.
OutputRate:	Desired output rate from specified counter.
actual_p:	Address where the actual programmed frequency should be stored. If this function fails, the actual frequency is not updated.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	Timer is not valid.

IOCTL Interface:

This function makes use of several ioctl() requests.

StartConversion6430

---

int StartConversion6430(int descriptor);

Description:

Issue a Start Convert (software trigger) command to a board.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for read access.

IOCTL Interface:

```
int rc;
struct DM6430HR_IO16 io_request;

/*
 * Read from Start Convert Register at base I/O address + 6
 */

io_request.reg = r_START_CONVERSION_6430;

/*
 * Any value works here because it is ignored making this request.  However, on return from
 * ioctl(), the member variable value contains the data read but in this case we're not interested
 * in the value at all … just the fact that the read was performed.
 */

io_request.value = 0;

rc = ioctl(descriptor, DM6430HR_IOCTL_INW, &io_request);
```

StartDMA6430

---

int StartDMA6430(int descriptor, enum DM6430HR_DMA DMAChannel, size_t TransferBytes);

Description:

Start DMA on a board's specified DMA circuit.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
DMAChannel:	DMA circuit to operate on. Valid values are DM6430HR_DMA1 and DM6430HR_DMA2.
TransferBytes:	Number of bytes to transfer in a single DMA. This value must be even because the entities transferred are 16-bit signed converted A/D values.

Return Value:

0:	Success.	
-1:	Failure with errno set as follows:	
	EACCES	descriptor refers to a file that is open but not for write access.
	EINVAL	DMAChannel is not valid.
	EINVAL	No DMA channel was ever allocated to DMAChannel.

EINVAL	No DMA buffer was ever allocated to DMAChannel.
EINVAL	TransferBytes is odd.
EINVAL	TransferBytes is greater than the DMA buffer size.

IOCTL Interface:

```
int rc;
struct DM6430HR_DST io_request;

/*
 * Target of operation is first DMA circuit
 */

io_request.dma = DM6430HR_DMA1;

/*
 * DMA transfer size is 4096 bytes (2048 words)
 */

io_request.length = 4096;

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_START, &io_request);
```

StopDMA6430

---

int StopDMA6430(int descriptor, enum DM6430HR_DMA DMAChannel);

Description:

Stop DMA on a board's specified DMA circuit.

Parameters:

descriptor:	File descriptor from OpenBoard6430() call.
DMAChannel:	DMA circuit to operate on. Valid values are DM6430HR_DMA1 and DM6430HR_DMA2.

Return Value:

0: Success.

-1: Failure with errno set as follows:

EACCES	descriptor refers to a file that is open but not for write access.
EINVAL	DMAChannel is not valid.
EINVAL	No DMA channel was ever allocated to DMAChannel.

IOCTL Interface:

```
int rc;

/*
 * Halt DMA on second DMA circuit
 */

rc = ioctl(descriptor, DM6430HR_IOCTL_DMA_STOP, DM6430HR_DMA2);
```

Example Programs Reference

Name	Remarks
dm6430-auto-burst	Demonstrates how to use the pacer clock, burst clock, sample counter, and channel/gain table to scan groups of channels multiple times.
dm6430-auto-scan	Demonstrates using the sample counter and pacer clock to do multi-scan sampling.
dm6430-dac	Demonstrates how to use the digital to analog converter.
dm6430-digital-interrupt	Demonstrates how to use advanced digital interrupts in event mode.
dm6430-digital-io	Demonstrates how to read and write the digital I/O ports. Uses port 0 for input and port 1 for output.
dm6430-dma	Demonstrates using DMA transfers to acquire data.
dm6430-dual-dma	Demonstrates using both DMA circuits on a board to transfer data.
dm6430-multi-burst	Demonstrates how to perform an analog to digital conversion on multiple channels using the channel/gain table.
dm6430-sample-counter	Demonstrates how to use the sample counter to generate interrupts.
dm6430-soft-trigger	Demonstrates how to initiate an analog to digital conversion using a software trigger.
dm6430-speed-test	Demonstrates three different IRQ handling and data read methods: 1) using a callback routine invoked via the driver interrupt handler sending a signal to the process; data is read using streaming input, 2) polling the IRQ counter for an interrupt circuit; data is read one sample at a time, and 3) polling the IRQ counter for an interrupt circuit; data is read using streaming input.
dm6430-stream	Demonstrates using streaming input to read blocks of data from the digital input FIFO.
dm6430-test-lib-errors	Test program to validate library error checking. This program exercises the error checking code added to the library. All exported functions are verified. The following types of tests are performed: 1) a function fails when expected, 2) if a function fails as expected. errno is set as expected depending upon the cause of failure, 3) a function succeeds when expected, and 4) if a function can accept multiple valid inputs, it succeeds on all combinations of such inputs.
dm6430-timers	Demonstrates how to program the 8254 programmable interval timers.
dm6430-user-timer	Demonstrates how to set up the User Timer to generate interrupts at a specified rate, poll the appropriate interrupt counter, and perform an A/D conversion when the counter changes.

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